

# **OPTIMIZATION OF PROCESS PARAMETERS INVOLVED IN LASER BENDING OPERATION USING TAGUCHI EXPERIMENTAL DESIGN METHOD**

A Project Report Submitted in Partial Fulfilment of the Requirements for the Degree of

**B. Tech.**

(Mechanical Engineering)

By

**PRATOH SOURAV SAHU**

Roll No. 10603039

*Under the supervision of*

**Prof. Saroj Kumar Patel**

Associate Professor

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Department of Mechanical Engineering  
**National Institute of Technology**  
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MAY, 2010

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# **National Institute of Technology**

## **Rourkela**

### **C E R T I F I C A T E**

This is to certify that the work in this thesis entitled **optimization of process parameters involved in laser bending operation using Taguchi experimental design method** by **Pratoh Sourav Sahu** has been carried out under my supervision in partial fulfilment of the requirements for the degree of **Bachelor of Technology** in *Mechanical Engineering* during session 2009- 2010 in the Department of Mechanical Engineering, National Institute of Technology, Rourkela.

To the best of my knowledge, this work has not been submitted to any other University/Institute for the award of any degree or diploma.

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# ABSTRACT

*A laser-bending process has many advantages such as no mechanical spring-back effect, precise incremental adjustment, high level of process flexibility, and the capability of production of complex shapes due to which it has shown a great promise and so has lately been the subject of considerable interest. This paper reports the variation of bending angle with change of different process parameters. Experiments are conducted following a well planned experimental schedule based on Taguchi's design of experiments (DOE) method and the optimal values of process parameters for maximum bending angle is thus determined. Process parameters include laser power, pulse diameter, pulse duration and scan speed. Significant control factors predominantly influencing the bending angle are also identified. Specimen used for experiments is Aluminium metal sheet and Nd-YAG laser is used as laser source.*

**Keywords:** laser bending, spring-back, DOE.

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## Chapter 1

# INTRODUCTION

### Background and Motivation

The incessant quest for higher efficiency and productivity across the entire spectrum of manufacturing and engineering industries has ensured that most modern-day components are subjected to manufacturing processes keeping a close relation between cost and rate of production. Laser bending has become a viable process for the shaping of metallic components. The laser bending process is of much importance to industries that previously relied on expensive stamping dies and presses for prototype evaluations on a large scale, relevant industry sectors include aerospace, automotive, and microelectronics. In contrast with conventional bending techniques this method requires no mechanical contact and hence offers many of the advantages of process flexibility and lower cycle time associated with other laser manufacturing techniques such as laser cutting and marking. Laser bending can produce metallic, predetermined shapes with minimal distortion. The process is similar to the well established torch flame bending used on large sheet material in the ship building industry but no doubt a great deal of more control of the final product can be achieved. One of the main characteristics of a laser-bending process is that it does not require use of hard tooling or external forces. Hence, a laser-bending process has many advantages such as no spring-back, high process flexibility, and the capability of production of complex shapes, structures and the formation of very small parts. Accordingly, over the years, many researchers have investigated not only the phenomena of the process, but also the realistic product applications in order to realize better achievements with the laser-bending process. Very rapid strides have been made on all fronts of science, processing, control, modelling, application developments etc. and this has made it an invaluable tool that is now being increasingly considered to be an integral part of component design. The laser beam techniques are eminently suited to modify a wide range of engineering properties. The properties that can be modified by adopting the laser technique include mechanical,



thermo-mechanical, electrochemical, optical, electrical and magnetic/acoustic properties.

The development of laser bending has been dynamic largely on account of the fact that it is a new field of science and technology that is being increasingly relied upon to meet all the key modern day technological requirements: material savings, enhanced efficiencies, accuracy, faster rate of production etc. The overall utility of this technique is further augmented by the fact that modifications to the component surface can be metallurgical, mechanical, chemical or physical.

One of the final goals of the laser-forming application is to make a target shape from a flat sheet metal automatically. The Laser forming process is realized by introducing thermal stresses into the surface of a workpiece. These internal stresses induce plastic strains bending the material or result in local elastic plastic buckling.

Garycheng and Yao [1] proposed the process synthesis in laser forming which is primarily concerned with determination of laser scanning paths and heat condition given a target shape to form. They reported the development of a process synthesis methodology for laser forming of a class of shapes based on the concept of genetic algorithm (GA).

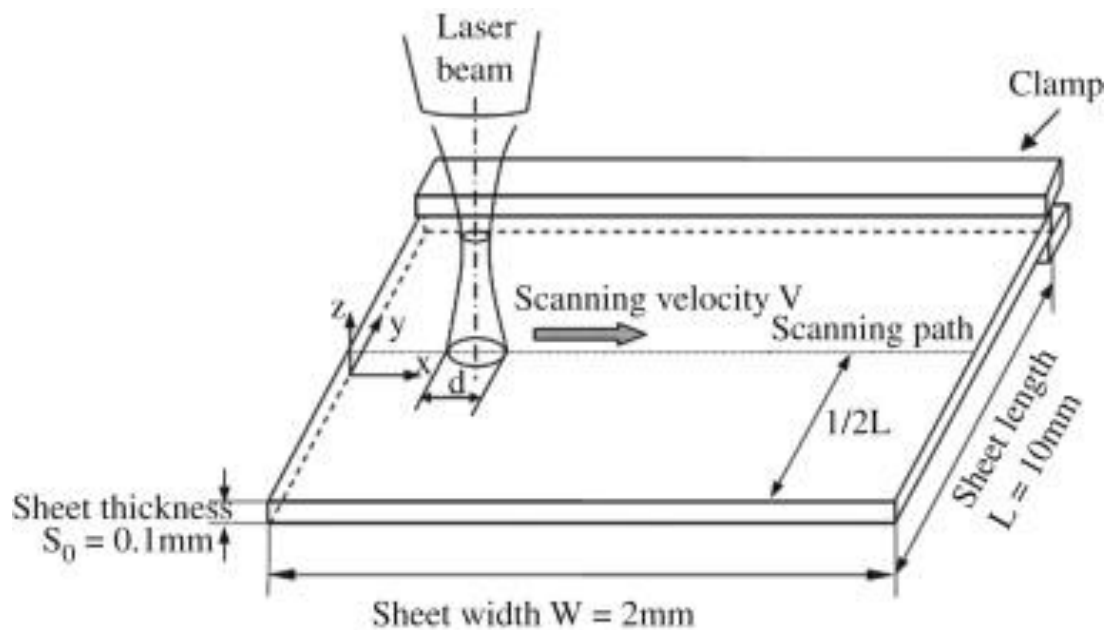
Cheng and Lin [2] precisely predicted the bending angles of sheet metal formed by laser using three supervised neural networks. Inputs to these neural networks were forming parameters such as beam spot diameter, scan speed, laser power, and workpiece geometries including sheet thickness and length of sheet metal workpiece.

Labeas [3] used numerical simulation of laser beam forming process to decide optimal process parameters resulting into desired bending patterns as well as to investigate forming limits of various components. They developed a local Finite Element simulation model, capable of predicting temperature fields and deformation shapes of laser beam-treated aluminium specimens. The numerical algorithm was based on a non-linear three-dimensional transient thermal-structural analysis, temperature-dependent thermal and mechanical material properties and of course a laser beam heat flux model.

Dubey and Yadava [4] used a hybrid approach of Taguchi method (TM) and principal component analysis (PCA) for multi-objective optimization (MOO) of pulsed Nd:YAG laser beam cutting (LBC) of nickel-based superalloy (SUPERNI 718) sheet to achieve better cut qualities within existing resources.

Marya and Edwards [5] derived a simple dimensionless equation to find process parameters in order to maximize bending angle and therefore assist in the optimization of the process conditions.

Against this background, the present study has been undertaken to optimize the process parameters involved in laser bending. Optimization technique is used to set the values of input parameters like laser power, scan velocity, spot diameter and pulse duration which are the controllable variables so as to get an optimum value of output.



**Fig 1.1:** Laser bending parameters



**Fig 1.2:** Laser machine setup

## Chapter 2

### LITERATURE REVIEW

This section provides an insight to the current technology available in the field of laser forming. It also highlights various methods used by researchers on this topic.

Laser forming is a complex transient process that involves thermodynamics, elastic-plastic mechanics, metallography etc. To control the deformation of metal sheet, research of mechanics plays the major role. Forming mechanisms are governed by the temperature field which in turn is influenced by geometry of workpiece, laser power, laser spot diameter, laser pulse duration, scanning velocity, scanning path and so on.

Here we get the feel of the topic by getting to know about various mechanisms governing laser forming, influence of various parameters on the laser forming operation.

Shichun and Jinsong [6] did the experimental study to find out the changes in the bending angle with process parameters. Process parameters consist of laser energy parameters, material parameters and sheet geometry parameters. The laser energy parameters include laser power, path feed-rate, beam spot diameter and feed number. Material parameters include coefficient of thermal expansion, density and specific heat at constant pressure. Sheet geometry parameters include sheet length, width and thickness. The experiments were performed on a type of LCM-408 laser machine, with a CO<sub>2</sub> laser source of 2 kW. Steel 08 (corresponding to AISI 1008), aluminium L3M (corresponding to ASTM 1050, annealed) and duralumin LY12CZ (corresponding to ASTM 2024, quenched and naturally aged) sheets were chosen as the working materials for the tests of laser bending. The sheet surfaces were coated with carbon black before testing in order to increase the absorption of laser power. The sheet metals after irradiation were cooled naturally. The conclusions

drawn from the tests were that the bending angle varied in direct proportion to the laser power and feed number, and in inverse proportion to the path feed-rate and beam spot diameter. The material parameters are related by a thermal-effect index, which can be related as  $R = \alpha_{th} / \rho c_p$ , where  $\alpha_{th}$  is the coefficient of thermal expansion,  $\rho$  is the density of the material and  $c_p$  is the specific heat capacity at constant pressure. The bending angle was found to be increasing with increase in the index  $R$ . There was no significant influence of the strength at room temperature on the bending angle. Among the sheet geometric parameters only sheet thickness had remarkable effect on the bending angle, which decreases sharply with increase in the sheet thickness.

Shen and Yao [7] did the experimental study of mechanical properties of sheet metal after laser irradiation. Many sheet metal components formed by mechanical pressing are subjected to cyclic loading during their service life. The investigations indicated that the fatigue performance of the pressed components decreased significantly compared to the stock plate specimens of the same material. This decrease in life is attributed not only to the increase in tensile residual stress but more importantly also to the degradation of the material gains resulting from the mechanical forming process. The observed decrease in fatigue life has led to a search for an alternative manufacturing process for enhancing the fatigue performance. Laser forming is a flexible manufacturing process that forms a metal sheet by means of thermal stresses induced by external heat instead of external force.

Some analytical models for bending angle induced by the straight line scan in laser bending have been presented, and numerical simulations have also been performed using various commercial codes for laser bending. In order to increase the plastic deformation, the method that of adding external forces or bending moments during the laser forming process has been applied. For a multi-scans study, numerical investigations have been carried out to examine the difference in temperature fields and plastic deformations between the two simultaneous laser scans and the sequential scans. The effects of scan intervals on the bending angle for two-scan laser forming along the same path were investigated using numerical simulation.

However, this study focused on the design of the fatigue life test, and the influence of the laser processing parameters on the fatigue life was of little concern. The objectives of this study are to characterize the mechanical properties of laser-formed samples. The tensile properties and the low-cycle fatigue life under different laser processing parameters were investigated. A fractographic examination was also made to understand the microscopic behaviours of the fatigue crack initiation and propagation.

Monotonic tensile behaviour of low carbon steel specimens with different laser processing parameters was investigated. The tensile properties of specimens after laser forming changed slightly compared to the unprocessed ones. Low-cycle fatigue damage and life of the specimens were compared with that of the unscanned ones. The enhancement in fatigue life as indicated by the laser-formed specimens was encouraging. SEM analysis also revealed the reason why laser-formed low carbon steel has a longer fatigue life than before laser forming. The compressive residual strain is the most important reason why the fatigue life of low carbon steel after laser forming improves.

Garycheng and Yao [1] developed a process synthesis methodology by genetic algorithm. GAs, which are optimization techniques based on probabilistic transition rules, have been successfully implemented for a wide range of problems in physical and social sciences, engineering and operations research, and computer sciences. GAs mimic the natural evolution process by which superior creatures evolve while inferior ones fade out from the population as generations go on. GAs have been proved to be a robust, simple-to-implement method, which can handle a large set of parameters. The disadvantages of GAs include their long computational time, and the semi-empirical nature of the algorithm parameter selection procedure. Here GA based approach was presented for process synthesis applicable to laser forming of a class of shapes. The synthesis scheme developed in this study has the advantage of being able to handling a large number of decision variables. This approach was validated through several cases. The effects of fitness function and control parameters of GAs (population size, crossover rate and mutation rate) on the convergence of the design process were also

investigated. It was demonstrated through this investigation that given a desired shape for the class of shapes concerned, the approach used was effective in determining the optimal values of diverse process parameters for laser forming process. It was also shown that it is able to handle a large number of decision variables. When the number of decision variables was close to 30, however, it took a large number of generations to achieve convergence. Investigations showed that the algorithm control parameters and the fitness function type have significant effects on the GA synthesis results. It was shown that a proper form of fitness function is important to balance among competing objectives, such as geometric accuracy, forming time, and energy consumption.

Kim and Na [8] developed a method for 3D laser forming of sheet metal by using a geometrical information rather than a complicated stress-strain analysis. Forming sheet metal by laser-induced thermal stress (laser forming) is considered to offer great potential for rapid prototyping and other flexible manufacturing. In order to apply the laser forming process to real 3D products, a method that encompasses the whole process planning, including the laser irradiation patterns, laser power, and travel speed, when the target shape is given. In this work a method for 3D laser forming of sheet metal is proposed by using a geometrical information rather than a complicated stress-strain analysis. Using this method the total calculation time is reduced considerably while affording strong potential for enhanced accuracy.

Hsieh and Lin [9] investigated numerically and experimentally the buckling mechanism of a thin metal tube during laser forming in this study. Metal tubes made of 304 stainless steel were heated by a CO<sub>2</sub> Gaussian laser beam, which induced the buckling phenomenon on the tube surface due to elastic-plastic deformation. This uncoupled thermal-mechanical problem was solved using a three-dimensional finite element method and was subsequently satisfactorily verified with displacement measurements. The transient bending angle and residual stress of the thin metal tube under specific operation conditions were also studied.



Guan et al. [10] established a three-dimensional coupled thermo-mechanical finite element model. The laser-forming process is a new flexible forming process without rigid tools and external force. The sheet metal is formed by internal localized thermal stress induced by laser. Material properties play an important role in laser forming. A three-dimensional coupled thermo-mechanical finite element model is established in this paper. The laser-bending process of a sheet blank is simulated numerically using the model. The relationship between the bending angle and material property parameters, such as Young's modulus, yield strength, coefficient of thermal expansion, specific heat, and thermal conductivity, are studied extensively by FEM simulation. The simulations show that the material with lower Young's modulus and yield strength can produce a larger bending angle. The thermal expansion coefficient is nearly in direct proportion to the bending angle. The bending angle decreases with the increase of the heat conductivity.

Magee et al. [11] developed a non-contact laser forming (LF) demonstrator system to demonstrate the process on a large primitive shape. A fundamental study was carried out which examined the effects of laser-forming parameters on tokens of an aluminium and a titanium alloy. Energy, geometrical and metallurgical influences were investigated and are summarized here. Results of the study showed that LF of these aerospace materials is possible using a large operating envelope of laser-processing parameters. A range of metallurgical effects resulted on the titanium alloy and these are traced here. Depending on how the energy input was supplied to the plate surface, various geometrical effects resulted. These effects are discussed. Using the knowledge gathered from the fundamental study, a prototype LF system was built. The components of the system and the forming of a primitive shape on it are discussed. Conclusions from the study indicate that the future work lies in the development of the demonstrator for primitive 3-D shapes and the integration of a knowledge-based system.

Shen et al. [12] proposed a new mechanism of laser forming. Laser forming is a complex thermal-mechanical process. To reveal the mechanisms dominating the



forming process is essential to control accurately the deformation of metal plate. Numerous efforts had been made to understand the mechanisms of laser forming. Proposed mechanisms mainly included temperature gradient mechanism, buckling mechanism and upsetting mechanism. However, in the investigation of laser forming, it is found that the above three mechanisms cannot explain fully the process of deformation. Based on the study of thermal transfer and elastic–plastic deformation, the above three mechanisms are further explained. In addition, a new mechanism, coupling mechanism, is proposed. To verify the validity of the mechanisms proposed, numerical simulations are carried out, and simulation results are consistent with analyses of mechanisms.

Ueda et al. [13] used temperature distribution for determining the bending angle. Laser forming is a thermal process for the deformation of sheet metal by inducing localized thermal stress. Temperature distribution is the most important factor for determining the bending angle of the sheet metal. In the present study, the combined effect of the temperature of the workpiece, the temperature gradient between the two surfaces of the sheet, the size of the area irradiated with laser beam, and the thickness of the workpiece is investigated both theoretically and experimentally. The temperature at the surface irradiated with CO<sub>2</sub> laser and at the opposite surface are simultaneously measured using two-color pyrometers with an optical fiber. The bending angle has been found to increase with the spot diameter and workpiece surface temperature and decrease with workpiece thickness.

Thomson and Pridham [14] discussed the development of a basic process monitoring and control system. Laser forming is a process that uses the energy of relatively high powered lasers to cause permanent deformation to components by inducing localized thermal stresses. This paper briefly discusses laser forming and the development of a basic process monitoring and control system used to overcome various problems due to the complex nature of the lasers and the manner in which they interact with material.

## Chapter 3

### **MATERIALS AND METHODS**

**Workpiece:** Aluminium metal sheet

**Dimensions of the specimen:-**

Length: 60 mm

Width: 20 mm

Thickness: 0.25 mm

**Laser machine used:** Nd-Yag laser

**Ranges of various laser parameters:-**

Frequency: 0.5 to 20 Hz

Laser power: 0 to 8.5 KW(500 V, 0.5 ms)

Pulse diameter: 0.2 to 2 mm

Pulse duration: 0.5 to 20 ms

Scan speed: 0 to 20 mm/sec

**Input parameters:**

Laser power

Pulse diameter

Pulse duration

Scan speed

**Output parameter:**

Bending angle

**Clamping device:**

The need of a proper clamping device was inevitable during the course of experimenting. Idea was to fix the metal sheet in a cantilever fashion so that it remains firm while laser irradiation was in progress. To accomplish this, two metal flats of 9 cm length, 2 cm width and 5 mm thickness were cut by shearing machine and then two holes drilled with the help of radial drilling machine. These flats were held together by allen screws whose pitch diameter was equal to that of the internal threads of holes provided in the surface plate of laser machine. Thus by tightening the allen screws metal sheet was held in position and removed by loosening the same, after conducting the experiment.



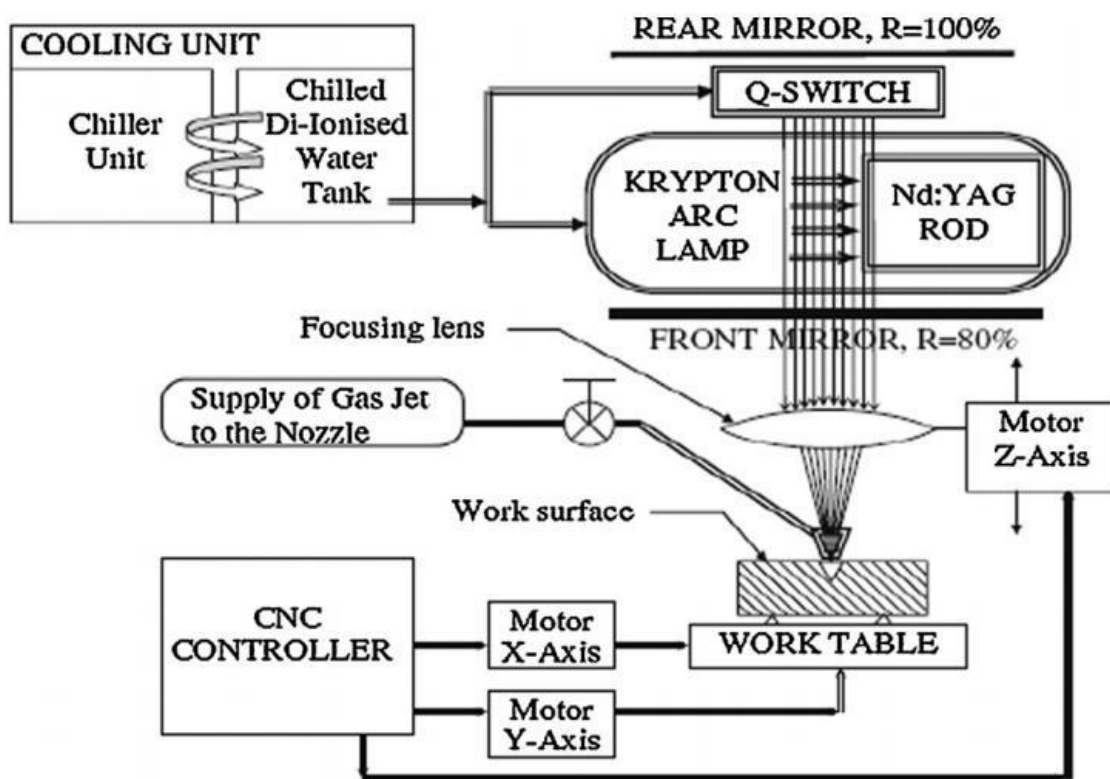
**Fig 3.1:** clamping device setup

**Working of laser machine:**

LASER is an acronym for light amplification by stimulated emission of radiation. By virtue of photons of same frequency, wavelength and phase laser light is quite different from ordinary light. Laser beams are highly directional, highly coherent,

have high power density, and better focussing characteristics. Laser machine involves machining which is non conventional thermal energy based. Material is removed by melting, chemical degradation and vaporization.

CO<sub>2</sub> and Nd:YAG lasers are mostly used in modern industries. Due to some unique features Nd:YAG gets preference over CO<sub>2</sub>. Dubey and Yadava [15] found that mean beam power is relatively low but the beam intensity is relatively high due to smaller pulse duration and better focussing behaviour. Smaller kerf width, micro-size holes, narrower heat affected zone(HAZ) and better cut edge kerf profile can be obtained in Nd:YAG laser machine. Some brittle materials like SiC ceramics can be machined due to smaller thermal load which is not possible with CO<sub>2</sub> laser. Nd:YAG laser is highly absorbed when falling even on a reflective surface due to its shorter wavelength. The enhanced transmission through plasma, wider choice of optical materials and flexibility in handling with the advent of fibre optic beam delivery are also important characteristics of Nd:YAG laser.



**Fig 3.2:** Schematic representation of Nd:YAG laser beam machine

Changing laser power only and keeping other parameters constant:-

Pulse diameter: 2 mm

Pulse duration: 0.5 mm

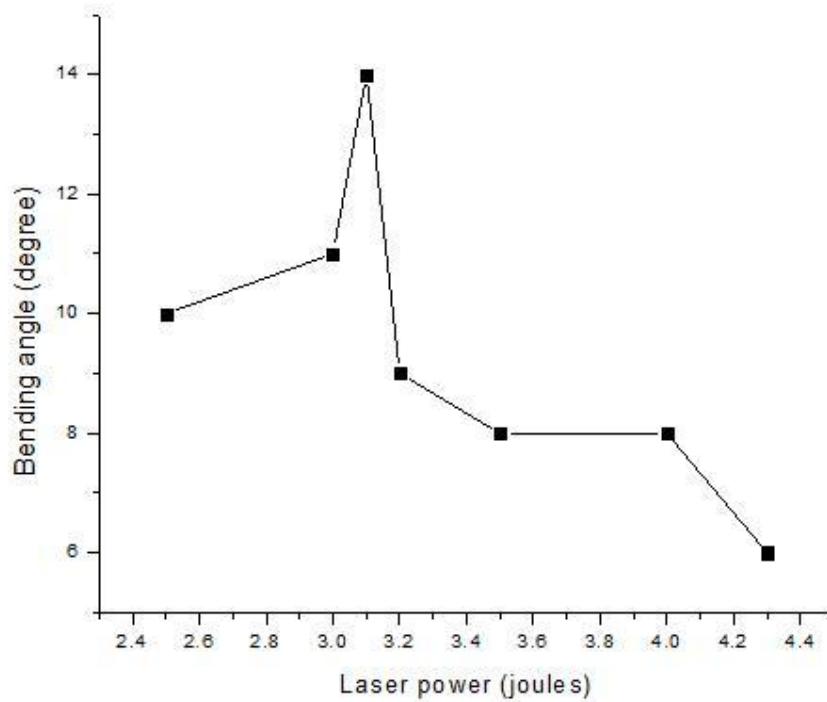
Frequency: 18 Hz

Scan speed: 25%

Number of passes: 8

**Table 3.1:** variation of bending angle with changing laser power

<b>Laser power(in joules)</b>	<b>Bending angle(in degree)</b>
2.5	10
3	11
3.1	14
3.2	9
3.5	8
4	8
4.3	6



**Fig 3.3:** laser power versus bending angle

Changing pulse diameter only and keeping other parameters constant:-

Laser power: 3J

Pulse duration: 0.5 ms

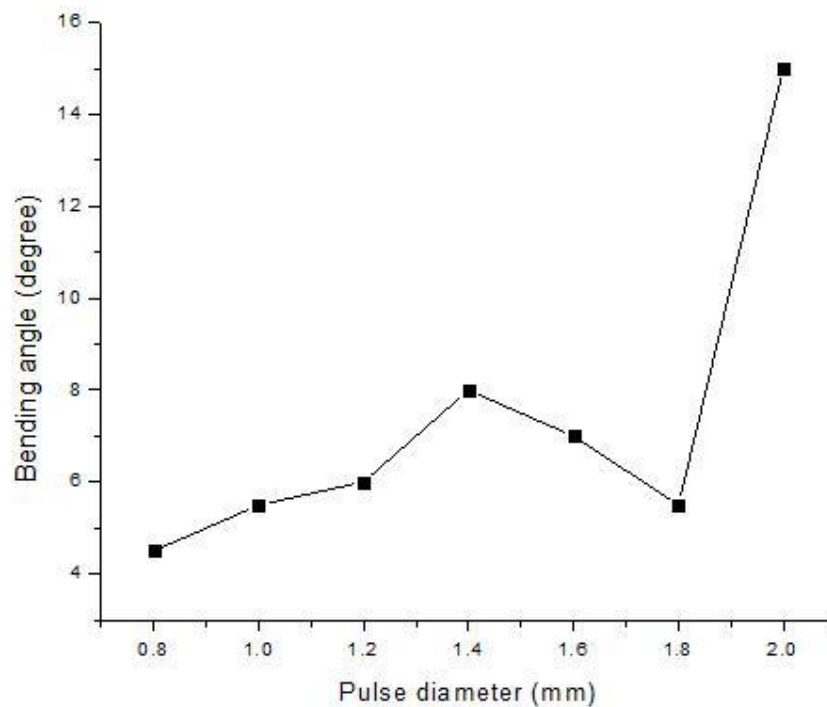
Scan speed: 25%

Frequency: 18 Hz

Number of passes: 8

**Table 3.2:** variation of bending angle with changing pulse diameter

Pulse diameter(in mm)	Bending angle(in deg)
2	15
1.8	5.5
1.6	7
1.4	8
1.2	6
1.0	5.5
0.8	4.5
0.6	damaged

**Fig 3.4:** Pulse diameter versus bending angle

Changing scan speed only and keeping other parameters constant:-

Laser power: 3J

Pulse diameter: 2 mm

Pulse duration: 0.5 ms

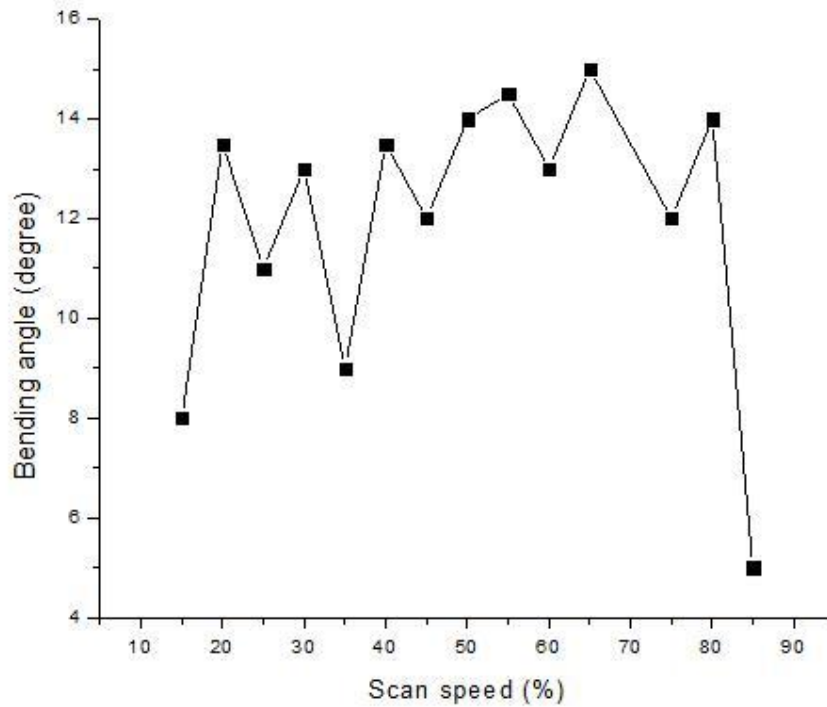
Frequency: 18 Hz

Number of passes: 8

**Table 3.3:** Variation of bending angle with changing scan speed

Scan speed(in %age)	Bending angle(in deg)
15	8
20	13.5
25	11
30	13
35	9
40	13.5
45	12
50	14
55	14.5
60	13
65	15
75	12
85	5
80	14





**Fig 3.5:** Scan speed versus bending angle

Changing pulse duration only and keeping other parameters constant:-

Laser power: 3J

Pulse diameter: 2 mm

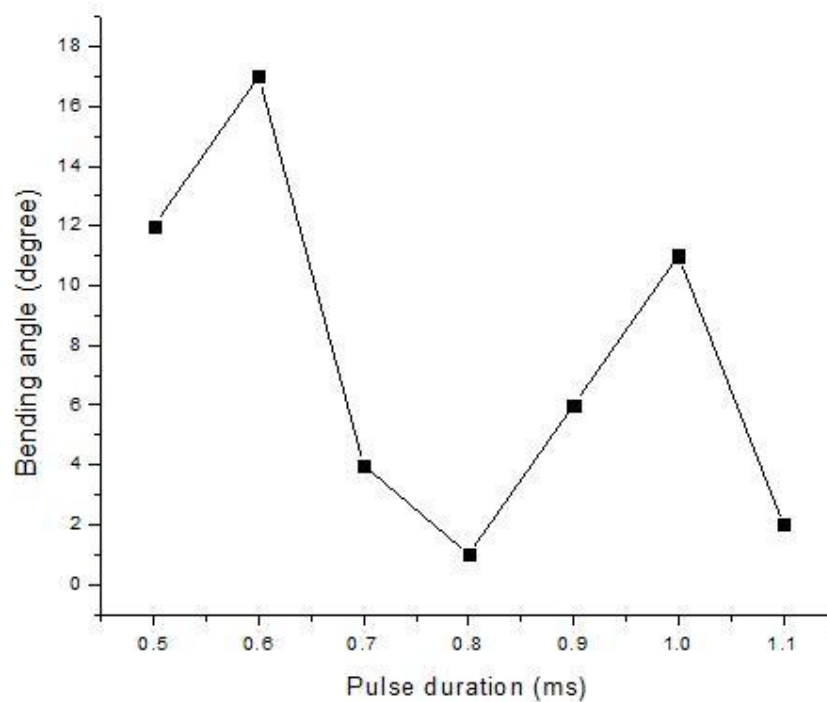
Scan speed: 25%

Number of passes: 8

Frequency: 18 Hz

**Table 3.4:** Variation of bending angle with changing pulse duration

Pulse duration(in ms)	Bending angle(in deg)
0.5	12
0.6	17
0.7	4
0.8	1
0.9	6
1	11
1.1	2

**Fig 3.6:** Pulse duration versus bending angle

Selecting 5 levels for each parameters required for design of experiment by Taguchi method:-

**Laser power levels:**

1	-	2.5 J
2	-	2.8J
3	-	3.1J
4	-	3.4J
5	-	3.7J

**Pulse diameter levels:**

1	-	1.2 mm
2	-	1.4 mm
3	-	1.6 mm
4	-	1.8 mm
5	-	2 mm

**Pulse duration levels:**

1	-	0.5 ms
2	-	0.6 ms
3	-	0.7 ms
4	-	0.8 ms
5	-	0.9 ms

**Scan speed levels:**

1	-	20%
2	-	30%
3	-	40%
4	-	50%
5	-	60%

**Table 3.5:** Control factors and their selected levels

Symbol	Factors	Unit	Level 1	Level 2	Level 3	Level 4	Level 5
A	Laser power	Joule	2.5	2.8	3.1	3.4	3.7
B	Pulse diameter	mm	1.2	1.4	1.6	1.8	2.0
C	Pulse duration	ms	0.5	0.6	0.7	0.8	0.9
D	Scan speed	%	20	30	40	50	60

**Table 3.6:** Experimental lay out and bending angles

Run number	Laser power (A)	Pulse diameter (B)	Pulse duration (C)	Scan speed (D)	Bending angle(in deg)
1	1	1	1	1	7.5
2	1	2	2	2	8
3	1	3	3	3	6
4	1	4	4	4	10
5	1	5	5	5	13

6	2	1	2	3	9
7	2	2	3	4	8
8	2	3	4	5	8
9	2	4	5	1	10
10	2	5	1	2	16
11	3	1	3	5	9
12	3	2	4	1	2
13	3	3	5	2	11
14	3	4	1	3	15
15	3	5	2	4	15
16	4	1	4	2	2
17	4	2	5	3	4
18	4	3	1	4	15
19	4	4	2	5	14
20	4	5	3	1	16
21	5	1	5	4	6
22	5	2	1	5	11
23	5	3	2	1	2
24	5	4	3	2	9
25	5	5	4	3	15

## Chapter 4

### RESULTS AND DISCUSSIONS

Laser bending involves a number of process variables, which contribute in a large way to the quality of bending achieved. During bending operation, various operating parameters are determined mostly based on past experience. It therefore does not provide the optimal set of parameters for a particular objective. In order to obtain the best result with regard to any specific bending characteristic, accurate identification of significant control parameters is essential. This chapter is devoted to analyze the experimentally obtained results on laser bending made at different operational conditions. For this purpose, a statistical technique called *Taguchi experimental design method* is used. Factors are identified according to their influence on the laser bending.

#### TAGUCHI EXPERIMENTAL DESIGN

Taguchi method of experimental design is a simple, efficient and systematic approach to optimize designs for performance and cost . In the present work, this method is applied to the process of laser bending for identifying the significant process variables influencing laser bending. The levels of these factors are also found out so that the process variables can be optimized within the test range.

#### Experimental Design

Experiments are carried out to investigate the influence of the four selected control parameters. The code and levels of control parameters are shown in table. This table shows that the experimental plan has five levels. A standard Taguchi experimental plan with notation  $L_{25}$  is chosen as outlined in table. In this method, experimental results are transformed into a signal-to-noise (S/N) ratio. It uses the S/N ratio as a measure of quality characteristics deviating from or nearing to the desired values. There are three categories of quality characteristics in the analysis of the S/N ratio, i.e. the lower-the-better, the higher-the-better, and the nominal-the-better. To obtain optimal bending angle, the higher-the-better quality characteristic is taken into consideration.

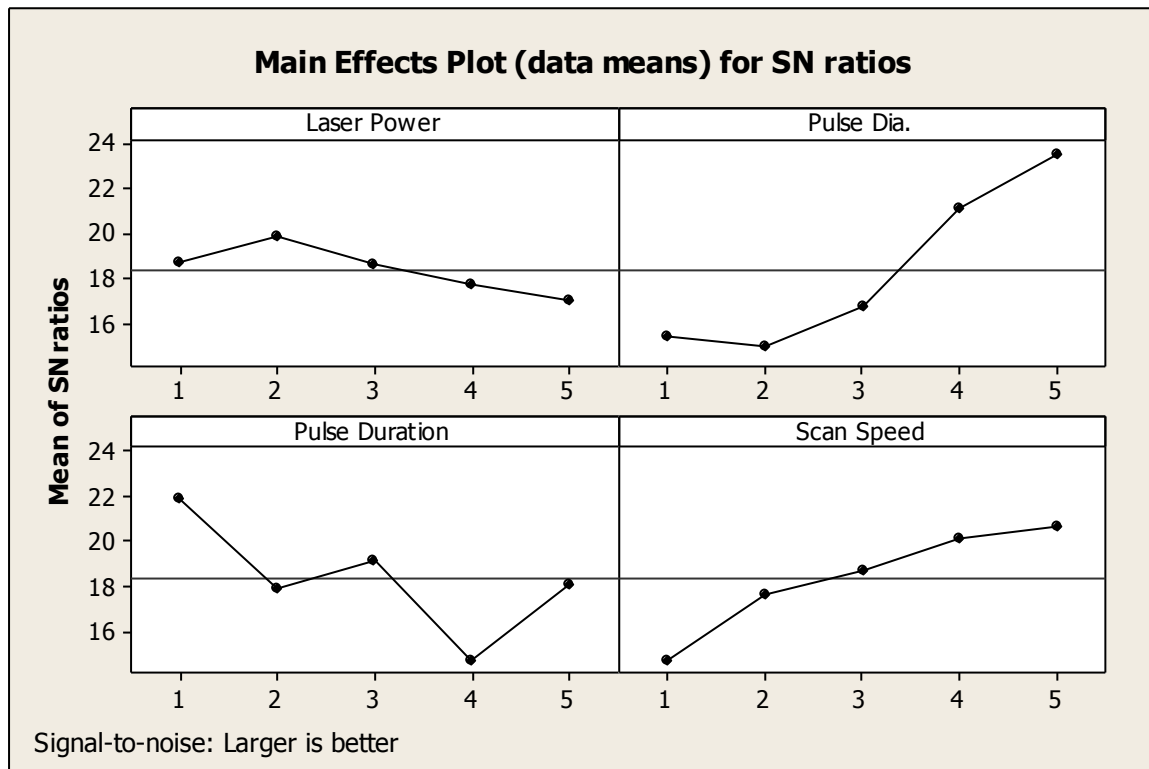
Determination of S/N ratio using MINITAB software package(trial version):

**Table 4.1:** S/N ratio values

Run number	Laser power (A)	Pulse diameter (B)	Pulse duration (C)	Scan speed (D)	Bending angle(in deg)	SNRA
1	1	1	1	1	7.5	17.5012
2	1	2	2	2	8	18.0618
3	1	3	3	3	6	15.5630
4	1	4	4	4	10	20.0000
5	1	5	5	5	13	22.2789
6	2	1	2	3	9	19.0849
7	2	2	3	4	8	18.0618

8	2	3	4	5	8	18.0618
9	2	4	5	1	10	20.0000
10	2	5	1	2	16	24.0824
11	3	1	3	5	9	19.0849
12	3	2	4	1	2	6.0206
13	3	3	5	2	11	20.8279
14	3	4	1	3	15	23.5218
15	3	5	2	4	15	23.5218
16	4	1	4	2	2	6.0206
17	4	2	5	3	4	12.0412
18	4	3	1	4	15	23.5218
19	4	4	2	5	14	22.9226
20	4	5	3	1	16	24.0824
21	5	1	5	4	6	15.5630
22	5	2	1	5	11	20.8279
23	5	3	2	1	2	6.0206
24	5	4	3	2	9	19.0849
25	5	5	4	3	15	23.5218





**Fig 4.1:** Mean of SN ratios versus factor levels

From the graphs of S/N ratio versus factor levels it is clear that the combination of laser power (level 2), pulse diameter(level 5), pulse duration(level 1) and scan speed(level 5) should give the maximum bending angle according to Taguchi design. So to confirm, an experiment was conducted with same set of parameters and the bending angle was observed to be  $20^0$  which was the maximum.

**Analysis of variance for bending angle using adjusted SS for tests:****Table 4.2:** Analysis of variance(general linear model)

Source	DF	Seq SS	Adj SS	Adj MS	F	P
Laser power	4	14.16	14.16	3.54	0.35	0.839
Pulse diameter	4	259.96	259.96	64.99	6.38	0.013
Pulse duration	4	81.76	81.76	20.44	2.01	0.187
Scan speed	4	39.96	39.96	9.99	0.98	0.470
Residual error	8	81.52	81.52	10.19	-----	-----
Total	24	477.36	-----	-----	-----	-----

**Analysis of control factor**

Table shows experimental lay out and results with calculated S/N ratios for laser bending angle. Analysis of the influence of each control factor on the bending angle is made with a signal-to-noise (S/N) response table, using MINITAB computer package(trial version). The response data of the testing process is presented in table. The control factor with the strongest influence is determined by difference values. The higher the difference, the more influential is the control factor. The strongest influence

on bending angle is found out to be of laser spot diameter(B) followed by pulse duration(C), scan speed(D), and laser power(A) respectively.

Response table for signal to noise ratios: larger is better

**Table 4.3:** The S/N response table for bending angle

Level	Laser power	Pulse diameter	Pulse duration	Scan speed
1	18.68	15.45	21.89	14.72
2	19.86	15.00	17.92	17.62
3	18.60	16.80	19.18	18.75
4	17.72	21.11	14.72	20.13
5	17.00	23.50	18.14	20.64
Delta	2.85	8.49	7.17	5.91
<b>Rank</b>	<b>4</b>	<b>1</b>	<b>2</b>	<b>3</b>

So the parameters in decreasing order of significance in laser bending operation is pulse diameter, pulse duration, scan speed and laser power.

## Chapter 4

### **CONCLUSIONS & SCOPE FOR FUTURE WORK**

#### **Conclusions**

This experimental investigation on the laser bending parameters have led to the following specific conclusions:

1. Laser spot diameter is the most significant factor followed by laser pulse duration, laser scanning speed and then laser power.
2. There is no specific pattern of variation of bending angle obtained by changing only one parameter while keeping the others constant.
3. Maximum bending angle predicted by Taguchi analysis for a particular set of parameters was found correct.

#### **Scope for future work**

This work leaves a wide scope for future investigators to explore many other aspects of laser beam bending. Some recommendations for future research include:

Application of other optimization techniques and comparing results with Taguchi method.

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